

# Standard Returnable Transport Packaging profile for TRACK 1140

This is the standard usage profile of a tracker attached to a returnable transport package (RTP). This profile guarantees the optimal way to capture the real behaviour of a waste container in a power efficient way.

Profile names: RTP STANDARD TRACK 1140

## When and how does the tracker determine and send location updates?



#### WHEN are locations determined?

Locations are by default captured based on the motion pattern of your asset.

This means when the tracker detects **that your asset starts or stops moving**, it will capture the location. Next to this, the tracker also captures a location every 24 hours. This is called a **periodic** location capture.

For every parameter a default setting is selected. Other settings can be chosen if needed for your asset tracking solution.

Parameter	Default	Other available settings	
When is a start detected?	Medium start sensitivity: A start is detected when the asset moved in 2 consecutive slots of 20 seconds.	High start sensitivity: A start is detected when the asset moved in 1 slot of 20 seconds.	
Are locations captured while moving?	No, locations are not captured while moving.	Yes,     Every 10 minutes     Every 20 minutes     Every 40 minutes     Every hour     Every 3 hours	
When is a stop detected?	A stop is detected when the asset has not moved for at least 30 minutes.	A stop is detected when the asset has not moved for  at least 5 minutes  at least 10 minutes  at least 1 hour	
Periodic location capture	Every 24 hours	<ul><li>Off</li><li>Every 12 hours</li><li>Every 48 hours</li></ul>	
Scheduled location capture	Off	Every day at 12 PM GMT	

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#### **HOW** are locations determined?

By default the tracker first scans for installed geobeacons to determine a location. If no geobeacons are found, the second choice is to scan for GPS signals to determine a location. Optionally, geobeacon localization can be disabled.

Parameter	Default	Other available settings
Localization technologies	$Geobeacon \to GPS$	GPS
GPS precision (CEP)	25 meters	4 meters <sup>1</sup>

### **HOW** is additional sensor information measured?

Optionally, different types of sensor information can be monitored by connecting BLE sensors to the tracker. It can then be chosen how often the measurements are done, and how often they are sent to the cloud.

It is also possible to use the internal orientation sensor to:

- Detect how an RTP is positioned.
- Know a specific state (lid open/closed, RTP folded or not).

Parameter	Default	Other available settings	
Orientation monitoring	Off	<ul> <li>Standard postions (reports the side of the tracker that faces up)</li> <li>Open/close (requires vertical postion of the tracker when open and horizontal position when closed. <sup>2</sup></li> <li>Anti-tamper functionality</li> </ul>	

# HOW and WHEN are locations and sensor information sent to the cloud?

Captured locations are **sent live to the platform.** The Sensolus patented **data integrity algorithm** to prevent data loss is enabled by default.

### Other parameters

neter	Default	Other available settings
dvertisments to make your tracker visible to phones and zone anchors	Off	On

<sup>&</sup>lt;sup>1</sup> In 80% of the cases

Want a customized tracker usage profile?
Contact Sensolus sales.

<sup>&</sup>lt;sup>2</sup> Contact Sensolus for more options